

# Real-Time (Paradigms) (1)

## 1. Temporal Specifications

RT systems are in essence *responsive (reactive)*, i.e. responding to events from the environment (user).

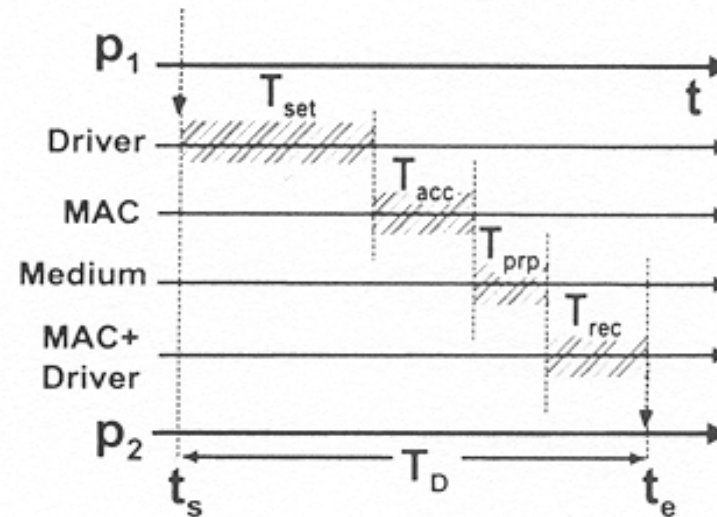
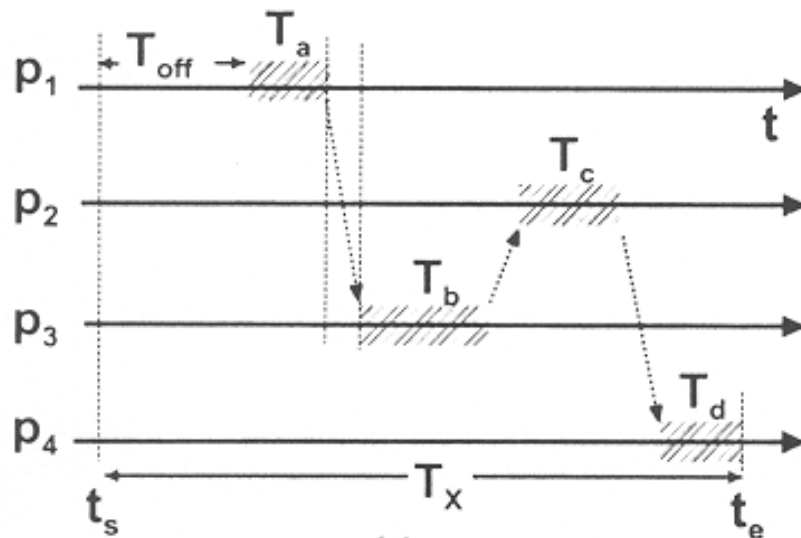
### Response Time

Interval between the occurrence of an input event and the first related output event

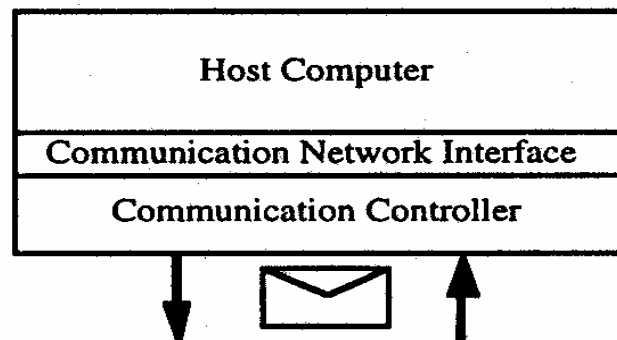
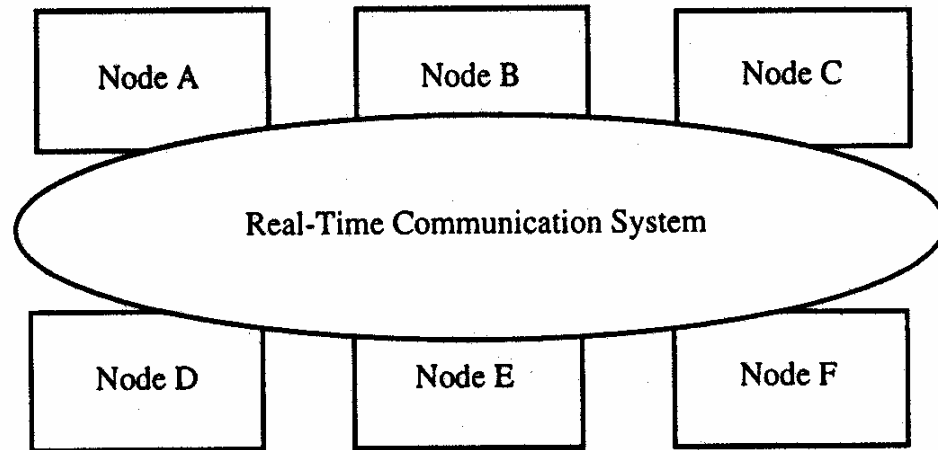
### Timed Action

Execution of an operation A such that its termination event happens within an interval  $T_A$  from a reference real time instant  $t_A$ .

### Timing Analysis of an action: (a) Computation (b) Communication



# Real-Time (Paradigms) (1a)

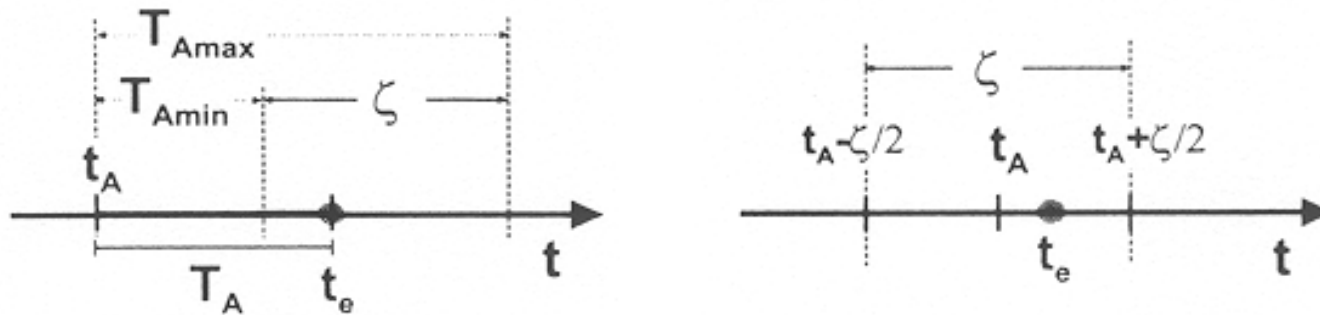


## Real-Time (Paradigms) (2)

### Jitter

variance in the duration of an action execution or imprecision in the positioning of its termination event.

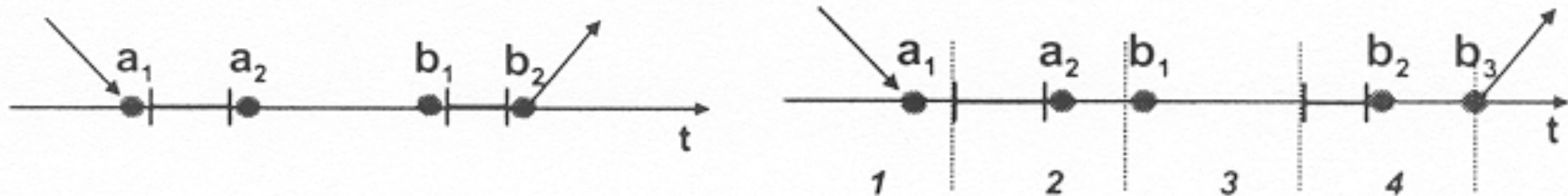
### Example



Mainly two approaches of triggering timed actions:

- *event-triggered*: system reacts upon the occurrence of an input event
- *time-triggered*: system reacts upon the command of a clock

### Example



## Real-Time (Paradigms) (3)

System predictability depends on the predictability of the inputs received from the environment which again depends on the class of application.

Trade-off:

Guaranteeing system predictability is simpler given a model assuming for regular (periodic) arrival patterns but: potential lack of coverage

Assuming a model accepting irregular (aperiodic) arrival patterns are closer to reality but: designing and proving that such systems are predictable is much more difficult

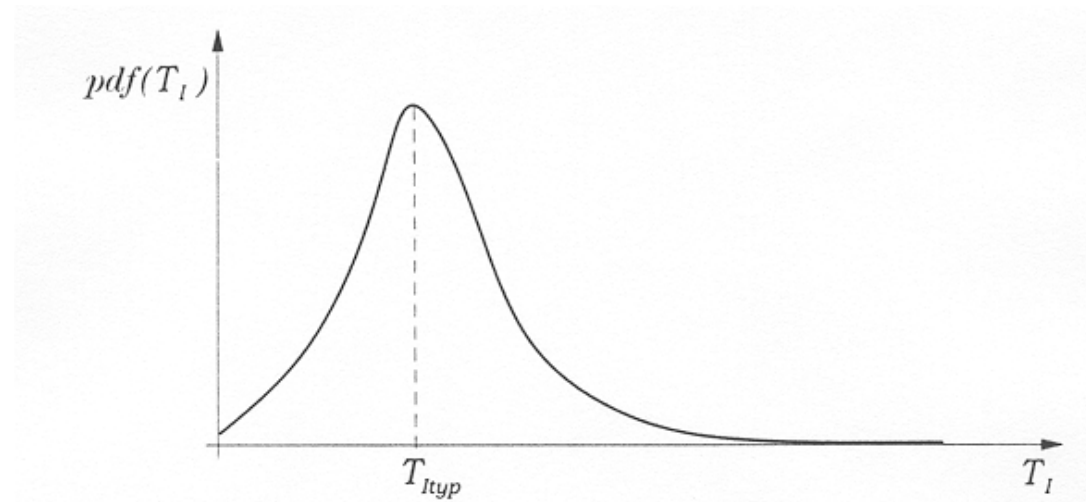
W.r.t the arrival of tasks, 3 types can be distinguished:

*Periodic* are such where tasks are released regularly at fixed rates (periods).

*Aperiodic* are such where tasks are released irregularly at some unknown and possibly unbounded rate.

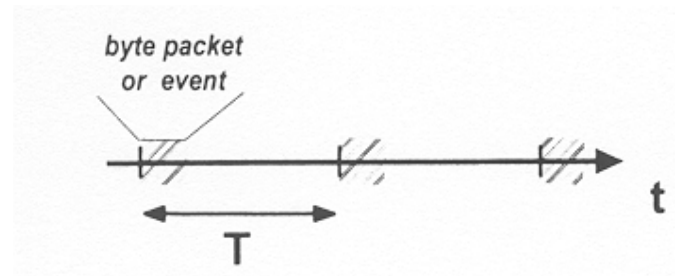
*Sporadic tasks* are such where tasks are released irregularly with some bounded rate. This rate is characterized by a minimum interarrival period.

### Aperiodic Distribution

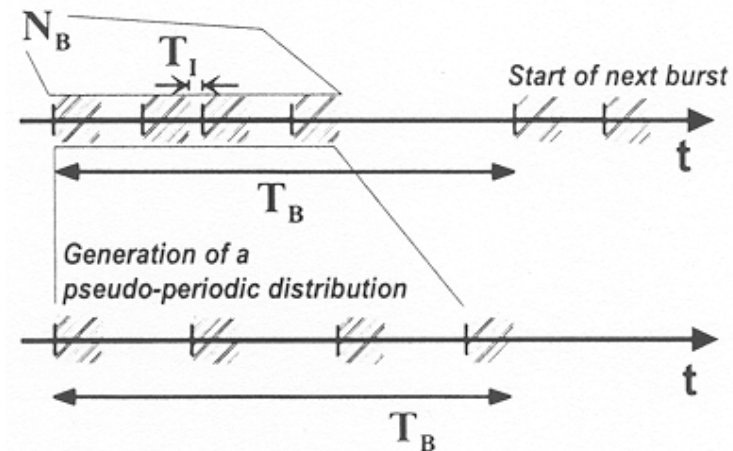


## Real-Time (Paradigms) (4)

### Periodic Distribution



### Sporadic Distribution



*burst period*  $T_B$ :

lower bound for the interval between the start of two consecutive bursts

*burst length*  $N_B$ :

upper bound of number of events occurring in one burst

*inter-arrival time*  $T_I$ : lower bound for the interval between the occurrence of two consecutive events

### Utilization Factor

measure of percentage a resource is used over a given time interval

## Real-Time (Paradigms) (5)

### 2a. Entities and Representatives

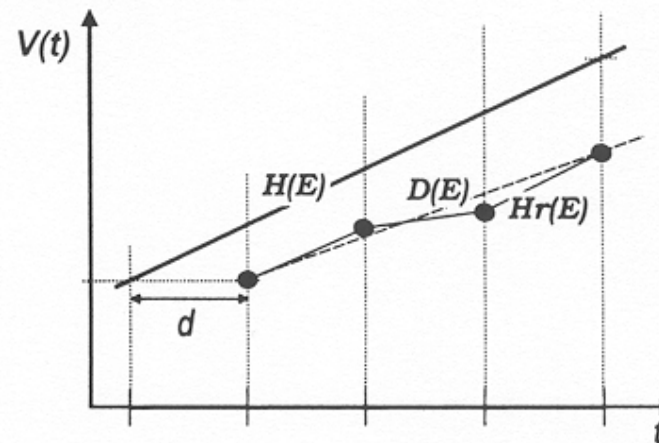
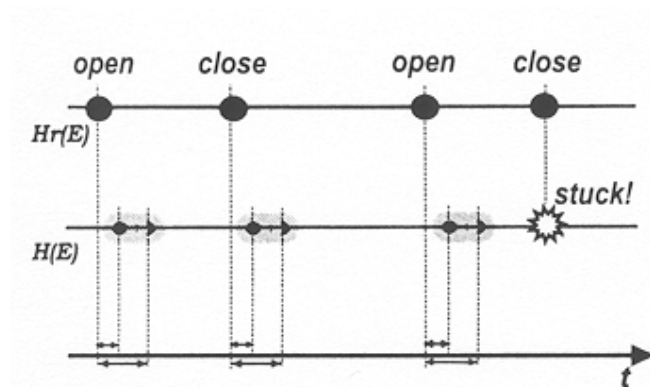
*RT entity*: element of the environment the state of which can be read or written, but not both

*Representative*: element of the (controlling) computer system which observes or acts on a RT entity's state

The state of a RT entity is not accurately reflected in its representative at all times during system evolution!

---> A representative emulates its RT entity with an error in the value of state, or in the time where this state holds, or both.

### Examples for RT Entity - Representative Relationship



## Real-Time (Paradigms) (6)

### 2b. Time-Value Duality

*Time-Value entity*: RT entity  $E$  the value  $V$  of which depends on time, i.e.  $V = E(t)$

For operations using time-value entities to be correct, two problems must be solved:

1. ensuring the correct observation of
  - the instantaneous value of the RT entity and
  - its positioning in the timeline, i.e. the corresponding time of the value
2. ensuring the correct use of the observation, i.e. using the observed value while it is still valid

ad 1)

Given a known  $V_0$ , observation  $(r(E_i)(t_i), T_i)$  is *consistent in the value domain*, if and only if  $v_i \leq V_0$

Given a known  $Z_0$ , observation  $(r(E_i)(t_i), T_i)$  is *consistent in the time domain*, if and only if  $\zeta_i \leq Z_0$

A set of observations is *mutually consistent*, if they are consistent and the timestamps of all observations fall within a given interval  $Z_m$  (also called *relative validity interval* in the context of databases)

ad 2)

Given a known  $V_a$ , observation  $(r(E_i), T_i)$  is *temporarily consistent at  $t_a \geq T_i$* ,

if and only if  $|E_i(t_a) - E_i(T_i)| \leq V_a$  (also called *absolute validity interval* in the context of databases)

The first problem addresses the consistency property w.r.t. the observation event, the second one deals with the evolution of the consistency of its value over time, a specific characteristics of time-value entities.